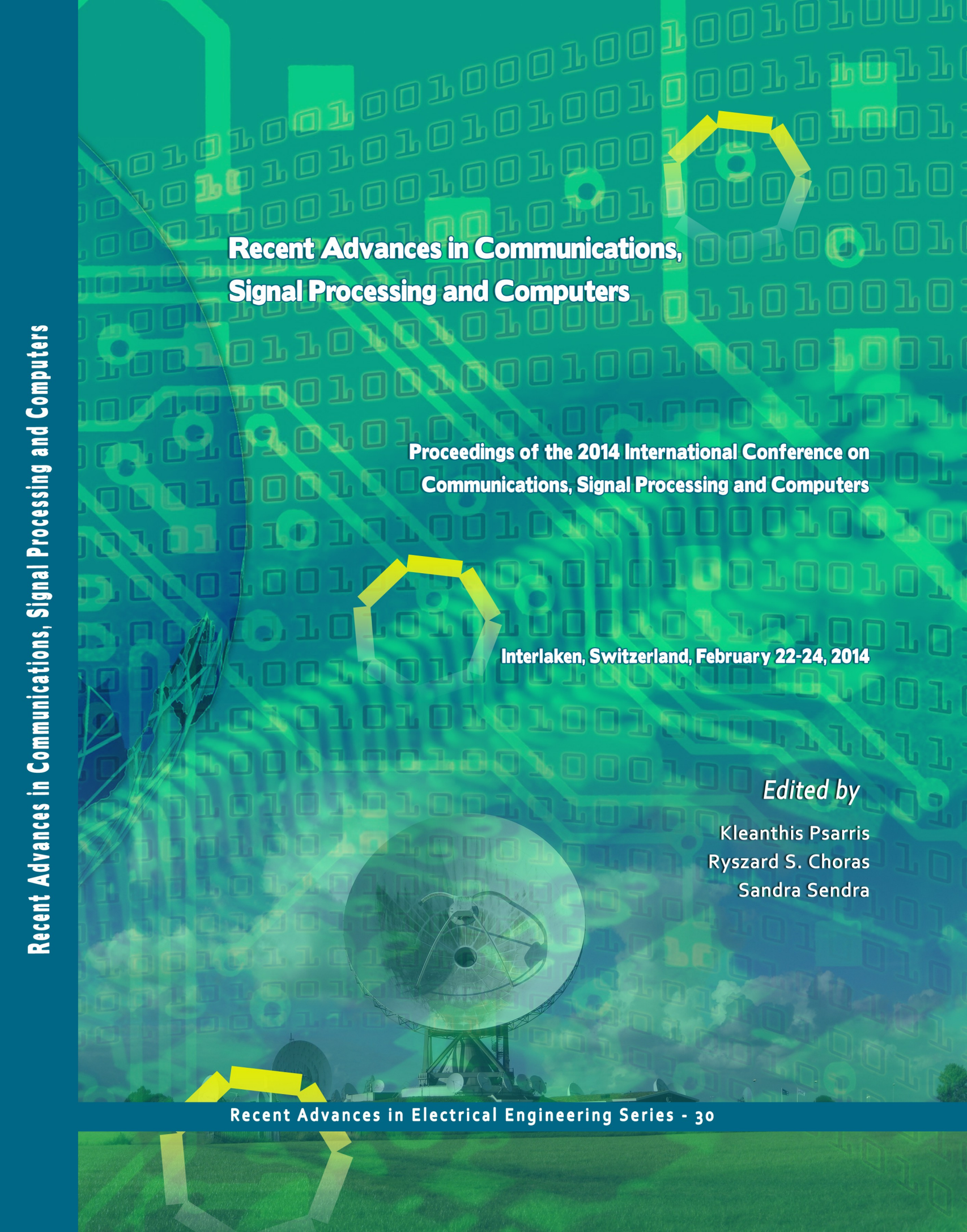

Recent Advances in Communications, Signal Processing and Computers

Proceedings of the 2014 International Conference on Communications, Signal Processing and Computers

Interlaken, Switzerland, February 22-24, 2014

Edited by

Kleanthis Psarris
Ryszard S. Choras
Sandra Sendra

Recent Advances in Electrical Engineering Series - 30

Recent Advances in Communications, Signal Processing and Computers

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Table of Contents

Plenary Lecture 1: Discrete Lyapunov Controllers for an Actuator in Camless Engines 12
Paolo Mercorelli

Plenary Lecture 2: EMG-Analysis for Intelligent Robotic based Rehabilitation 13
Thomas Schrader

Plenary Lecture 3: Atmospheric Boundary Layer Effects on Aerodynamics of NREL Phase VI Windturbine in Parked Condition 14
Mohammad Moshfeghi

Plenary Lecture 4: Laminar and Turbulent Simulations of Several TVD Schemes in Two-Dimensions 15
Edisson S. G. Maciel

Plenary Lecture 5: The Flocking Based and GPU Accelerated Internet Traffic Classification 17
Zhiguang Xu

Plenary Lecture 6: The State of Civil Political Culture among Youth: Goals and Results of Education 18
Irina Dolinina

Signal Processing in Power State Variables for Sound and Electromagnetic Environment by Introducing Fuzzy Probability 19
Akira Ikuta, Hisako Orimoto

Second Order Statistics of SC Receiver Output SIR in the Presence of α-k-μ Multipath Fading and Co-Channel Interference 27
S. Jovkovic, D. Milic, D. Djosic, S. Panic, S. Veljkovic, C. Stefanovic

Subdivided Weight Interpolation based on Multiscale Gradients for Color Filter Array 32
Yonghoon Kim, Jechang Jeong

Implementation of Sparse Representation Classifier (SRC) to Heartbeat Biometrics 36
W. C. Tan, D. A. Ramli

Stochastic Modeling of Sound Environment System with Multiplicative Noise and Noise Cancellation Method 43
Hisako Orimoto, Akira Ikuta

A Novel Symmetric Text Encryption Algorithm based on Logistic Map 49
M. A. Murillo-Escobar, F. Abundiz-Pérez, C. Cruz-Hernández, R. M. López-Gutiérrez

Deterministic Sequences from a Fibonacci Series For PAPR Reduction in SLM-OFDM Systems 54
Saheed A. Adegbite, Scott G. McMeekin, Brian G. Stewart

Classification of Intravascular Ultrasound Signal by Kernel Density Estimation and Bayes Theorem for Identification of Coronary Plaque Tissue 60
Hiroki Tanaka, Kazuhiro Tokunaga, Eiji Uchino, Noriaki Suetake

Automated Surveys and Integrated Auto-Location by Laser Scanner and GPS 65
V. Barrile, G. Bilotta

PA-SLNR Multi-User MIMO Precoding Based on GSVD 73
Varun Jeoti, Elsadig Saeid

Detection of Lightning Pattern Changes Using Machine Learning Algorithms 78
Aimee Booysens, Serestina Viriri

Multiple Types of Heterogeneous Spatial Data Integration Process Using Business Intelligence Approach 85
M. Mustafa, A. Aliff, M. Yazid

An Approach to Enhance Security in the Access Layer of the IMS Networks 89
E. Belmekki, M. Bellafkih, A. Belmekki

Quality based Speaker Verification Systems using Fuzzy Inference Fusion Scheme 96
L. A. Hamid, D. A Ramli

Fault Tolerance and Load Balancing on the Example of GlassFish 104
Arne Koschel, Michael Heine, Lars Knemeyer, Irina Astrova

Laser Based Tomographic System for Visualization and Characterization of Tissue Optical Phantoms 108
R. Sivakumar, N. Sujatha

A Suitable Approach for Evaluating Bus Arrival Time Prediction Techniques in Egypt 113
M. Tantawy, M. Zorkany

Considering Partially Developed Artifacts in Change Impact Analysis Implementation 118
Nazri Kama, Sufyan Basri, Roslina Ibrahim

Modeling and Performance Analysis of PCI Express 125
Miguel Angel Orozco, Mario Siller, Adán Ruiz

Monitoring Land-Cover Changes Using Satellite Imagery 131
Wayne Goosen, Serestina Viriri

PSCM: Proxy Server Cache Mechanism for Video on Demand System 138
Saleh Ali Alomari, Putra Sumari

Comparative Study of Different Methods for Measurement of "Smartness" of Smart Devices 145
Ahmet Al Zarqa, Tarik Ozkul, A. R. Al-Ali

A High End Capacity in Digital Image Steganography: Empowering Security by Mottling through Morphing 151
Sanjay Bajpai, Kanak Saxena

Sparse Feature Based Analysis of RF Signal for Coronary Plaque Tissue Classification with Reference to the Neighboring Information of the Target Tissue 157
Shota Furukawa, Eiji Uchino, Tadahiro Azetsu, Noriaki Suetake

Fixed-Point Implementation of Classifier for Tropical Wood Recognition System 161
Enas Dhuhri Kusuma, Rubiyah Yusof, Mohammad Fauzi Othman

A Method for Context Aware Web Service Discovery 167
Vahab Ghasemi, Hasan Haghighi

Comparative Study on Different Classifiers for Frog Identification System Based on Bioacoustic Signal Analysis 172
H. Jaafar, D. A Ramli, B. A. Rosdi

Early Termination of Transform Skip Mode for High Efficiency Video Coding 177
Do-Kyung Lee, Miso Park, Hyung-Do Kim, Je-Chang Jeong

Pathloss Analysis at 900 MHz for Outdoor Environment 182
Zia Nadir, Mohammed Bait-Suwailam

Simulation and Analysisof a Full Duplex DWDM RoF System Using Optimized Phase Modulator and an OADM 187
Joseph Zacharias, Raji K., Vijayakumar Narayanan

Fingerprint Image Encryption based on Rossler Map 193
F. Abundiz-Perez, C. Cruz-Hernandez, M. A. Murillo-Escobar, R. M. Lopez-Gutierrez

Design of Compact RF Filters with Narrow Band-Pass and Wide Stop-Band by Open-Stub & T-shaped Microstrip Resonators and Defected Ground Structure (DGS) 198
Shervin Amiri, Nafiseh Khajavi, Mahboubeh Khajavi

Authors Index 203

Plenary Lecture 1

Discrete Lyapunov Controllers for an Actuator in Camless Engines

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Abstract: This paper deals with a hybrid actuator composed by a piezo and a hydraulic part controlled using two cascade Lyapunov controllers for camless engine motor applications. The idea is to use the advantages of both, the high precision of the piezo and the force of the hydraulic part. In fact, piezoelectric actuators (PEAs) are commonly used for precision positionings, despite PEAs present nonlinearities, such as hysteresis, satura- tions, and creep. In the control problem such nonlinearities must be taken into account. In this paper the Preisach dynamic model with the above mentioned nonlinearities is considered together with cascade controllers which are Lyapunov based. The sampled control laws are derived using the well known Backward Euler method. An analysis of the Backward and Forward Euler method is also presented. In particular, the hysteresis effect is considered and a model with a switching function is used also for the controller design. Simulations with real data are shown.

Brief Biography of the Speaker: Paolo Mercorelli received the (Laurea) M.S. degree in Electronic Engineering from the University of Florence, Florence, Italy, in 1992, and the Ph.D. degree in Systems Engineering from the University of Bologna, Bologna, Italy, in 1998. In 1997, he was a Visiting Researcher for one year in the Department of Mechanical and Environmental Engineering, University of California, Santa Barbara, USA. From 1998 to 2001, he was a Postdoctoral Researcher with Asea Brown Boveri, Heidelberg, Germany. From 2002 to 2005, he was a Senior Researcher with the Institute of Automation and Informatics, Wernigerode, Germany, where he was the Leader of the Control Group. From 2005 to 2011, he was an Associate Professor of Process Informatics with Ostfalia University of Applied Sciences, Wolfsburg, Germany. In 2010 he received the call from the German University in Cairo (Egypt) for a Full Professorship (Chair) in Mechatronics which he declined. In 2011 he was a Visiting Professor at Villanova University, Philadelphia, USA. Since 2012 he has been a Full Professor (Chair) of Control and Drive Systems at the Institute of Product and Process Innovation, Leuphana University of Lueneburg, Lueneburg, Germany.
Research interests: His current research interests include mechatronics, automatic control, signal processing, wavelets; sensorless control; Kalman filter, camless control, knock control, lambda control, robotics.

The full paper of this lecture can be found on page 19 of the Proceedings of the 2014 International Conference on Circuits, Systems and Control, as well as in the CD-ROM proceedings.

Plenary Lecture 2

EMG-Analysis for Intelligent Robotic based Rehabilitation

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Abstract: The establishment of wireless sensor network (WSN) technology in physiotherapy and rehabilitation is a clue for improvement of the thera- peutic process, quality assessment and development of supporting tech- nologies such as robotics. Especially for complex therapeutic interventions such as sensorimotor training, a continuous monitoring during the ther- apy as well as for all sessions would be quite useful. For the usage of robotic support in rehabilitation various input informa- tion about the status of patient and his/her activity status of various muscles have to be detected and evaluated. The critical point for robotic intervention is the response time. Under physiotherapeutic and rehabilita- tion conditions, the robotic device should be able to react differently and in various patterns. A complex analysis procedure of input signals such as EMG is essential to ensure an effective response of the robot. However sensor nodes in a wireless (body) area network have limited resources for calculating and storage processes. A stepwise procedure with distributed analysis tasks is proposed. Electromyogram (EMG) measurements of eight muscles were collected and evaluated in an experimental setting of a sensorimotor training using different types of balance boards. Fast and easy methods for detection of activity and rest states based on time domain analysis using low pass IIR filter und dynamic threshold adaption. These procedures can be done on the sensor nodes themselves or special calculation nodes in the network. More advanced methods in frequency domain or analysis of dynamical system behavior request much more system power in calculation as well as storage. These tasks could be done on the level of mobile devices such as mobile phones or tablet computer. A broad range of resources can be provided by cloud/internet. Such level based organization of analysis and system control can be com- pared with biological systems such as human nervous system.

Plenary Lecture 3

Atmospheric Boundary Layer Effects on Aerodynamics of NREL Phase VI Windturbine in Parked Condition

Professor Mohammad Moshfeghi
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Abstract: In a natural condition, the wind is affected by the groundcover and the type of terrains which impose vertical velocity profile to the wind. This wind profile, which is also called atmospheric boundary layer (ABL), dramatically influences the aerodynamic behaviors and loadings of horizontalaxis wind turbines. However, for the sake of simplicity, many numerical simulations only deal with the uniform wind speed. To consider the effects of the ABL, numerical simulations of the two-bladed NREL Phase VI wind turbines aerodynamicat the parked condition are conducted under both uniform and ABL. The Deaves-Harris (DH)model is applied to the ABL. The wind turbine blades are kept at the six o'clock position and are considered at two different pitch angles. The aerodynamic forces and moments of the uniform the DH model are compared.The results show that the pitch angle at which the HAWT is parked plays an important role on the blade loading. Also it is observed that for the fully separated conditions, the Down-blade and the blade in the uniform wind are under approximately similar aerodynamic loadings, while the Up-blade encounters more aerodynamic loads, which is even noticeable value for this small wind turbine. This in turn means that for an appropriate and exact design, effects of ABL should be considered with more care.

Brief Biography of the Speaker: Dr. Mohammad Moshfeghi works in Multi-phenomena CFD Engineerng Research Center (ERC) Sogang University, Seoul, South Korea. He is also Lecturer in Qazvin Azad University. He has a registered patent: "Split-Blade For Horizontal Axis Wind Turbines" (Inventors: Mohammad Moshfeghi, Nahmkeon Hur).

Plenary Lecture 4

Laminar and Turbulent Simulations of Several TVD Schemes in Two-Dimensions

Professor Edisson S. G. Maciel
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Abstract: This work, first part of this study, describes five numerical tools to perform perfect gas simulations of the laminar and turbulent viscous flow in two-dimensions. The Van Leer, Harten, Frink, Parikh and Pirzadeh, Liou and Steffen Jr. and Radespiel and Kroll schemes, in their first- and second-order versions, are implemented to accomplish the numerical simulations. The Navier-Stokes equations, on a finite volume context and employing structured spatial discretization, are applied to solve the supersonic flow along a ramp in two-dimensions. Three turbulence models are applied to close the system, namely: Cebeci and Smith, Baldwin and Lomax and Sparlat and Allmaras. On the one hand, the second-order version of the Van Leer, Frink, Parikh and Pirzadeh, Liou and Sreffen Jr., and Radespiel and Kroll schemes is obtained from a "MUSCL" extrapolation procedure, whereas on the other hand, the second order version of the Harten scheme is obtained from the modified flux function approach. The convergence process is accelerated to the steady state condition through a spatially variable time step procedure, which has proved effective gains in terms of computational acceleration (see Maciel). The results have shown that, with the exception of the Harten scheme, all other schemes have yielded the best result in terms of the prediction of the shock angle at the ramp. Moreover, the wall pressure distribution is also better predicted by the Van Leer scheme. This work treats the laminar first- and second-order and the Cebeci and Smith second- order results obtained by the five schemes.

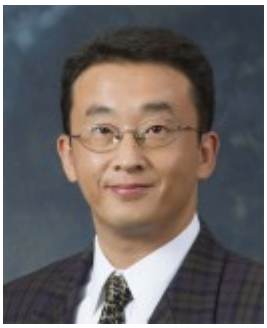
Brief Biography of the Speaker: Professor Edisson Sávio de Góes Maciel was born in Recife, Pernambuco, Brazil in 1969, February, 25. He studied in Pernambuco until obtains his Master degree in Thermal Engineering, in 1996, August. With the desire of study aerospace and aeronautical problems using numerical methods as tools, he obtains his Doctor degree in Aeronautical Engineering, in 2002, December, in ITA and his Post-Doctor degree in Aerospace Engineering, in 2009, July, also in ITA. He is currently Professor at UFGD (Federal University of Great Dourados) – Mato Grosso do Sul – Brasil. He is author in 47 papers in international journals, 2 books, 67 papers in international conference proceedings. His research interestes includes a) Applications of the Euler equations to solve inviscid perfect gas 2D and 3D flows (Structured and unstructured discretizations) b) Applications of the Navier-Stokes equations to solve viscous perfect gas 2D and 3D flows (Structured and unstructured discretizations) c) Applications of the Euler and Navier-Stokes to solve magneto gas dynamics flows 2D and 3D; (Structured and unstructured discretizations) d) Applications of algebraic, one-equation, and two-equations turbulence models to predict turbulent effects in viscous 2D flows (Structured and unstructured discretizations), e) Study of artificial dissipation models to centered schemes

in 2D and 3D spaces (Structured and unstructures discretizations) f)Applications of the Euler and Navier-Stokes equations to solve reentry flows in the Earth atmosphere and entry flows in Mars atmosphere in 2D and 3D (Structured and unstructured discretizations).

The full paper of this lecture can be found on page 79 of the Proceedings of the 2014 International Conference on Mechanics, Fluid Mechanics, Heat and Mass Transfer, as well as in the CD-ROM proceedings.

Plenary Lecture 5

The Flocking Based and GPU Accelerated Internet Traffic Classification



Professor Zhiguang Xu
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Abstract: Mainstream attentions have been brought to the issue of Internet traffic classification due to its political, economic, and legal impacts on appropriate use, pricing, and management of the Internet. Nowadays, both the research and operational communities prefer to classify network traffic through approaches that are based on the statistics of traffic flow features due to their high accuracy and improved robustness. However, these approaches are faced with two main challenges: identify key flow features that capture fundamental characteristics of different types of traffic in an unsupervised way; and complete the task of traffic classification with acceptable time and space costs. In this paper, we address these challenges using a biologically inspired computational model that imitates the flocking behavior of social animals (e.g. birds) and implement it in the form of parallel programs on the Graphics Processing Unit (GPU) based platform of CUDA from NVIDIA™. The experimental results demonstrate that our flocking model accelerated by GPU can not only effectively select and prioritize key flow features to classify both well-known and unseen network traffic into different categories, but also get the job done significantly faster than its traditional CPU-based counterparts due to the high magnitude of parallelism that it exhibits.

Brief Biography of the Speaker: Prof. Zhiguang Xu received his Ph.D. in Computer Science from University of Central Florida, FL, USA in 2001. He is currently Professor of Computer Science in the Department of Math and Computer Science at Valdosta State University, GA, USA. His research and teaching interests include Computer Networking, Artificial Intelligence, Parallel and Distributed Computing, and Computer Science Education. Professor Xu is author or co-author of more than 25 published papers in refereed journals or conference proceedings. He has been awarded many grants from both academic and industrial entities. He is actively serving as committee member, reviewer, or lecturer of many national and international conferences and organizations.

The full paper of this lecture can be found on page 88 of the Proceedings of the 2014 International Conference on Mathematical Methods, Mathematical Models and Simulation in Science and Engineering, as well as in the CD-ROM proceedings.

Plenary Lecture 6

The State of Civil Political Culture among Youth: Goals and Results of Education

Professor Irina Dolinina
Perm National Research University, Russia
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Abstract: Political culture is viewed as a phenomenon of social reality. Attitudes toward it (its meaning or significance) are historically conditioned. This research studies enduring presuppositions about (dispositions toward) society and the state, and how these are reflected in conscious stereotypes and cognitive structures among young people within the sociocultural mechanisms that form and modify the basic characteristics of political culture.

Brief Biography of the Speaker: Prof. Irina Dolinina was born in 1960, in Perm, Russia. She is Team Leader in the Research Project «Formation of the political culture of the students», and Professor of Philosophy and Law of the Faculty of Humanities, Perm National Research Technical University since 2012. She has received a lot of honors and awards (2012 - Diploma of the All-Russian Roswitha fund national education and the Education Committee of the State Duma of the Federal Assembly of the Russian Federation. 2013 - Diploma of the All-Russian Roswitha fund national education and the Education Committee of the State Duma of the Federal Assembly of the Russian Federation. Diploma-Russian contest "Best Science Book in the humanitarian sphere - 2013). Prof. Dolinina has various progessional organizations and activities.
(Expert on the legislative activities of the Council of Federation of Russia. Board member of the Interregional Association "For civic education." Director of the Research Centre of the political culture).

The full paper of this lecture can be found on page 57 of the Proceedings of the 2014 International Conference on Educational Technologies and Education, as well as in the CD-ROM proceedings.